Cross-correlation and automated classification: methods and tools

F.-X. Pineau¹

¹ CDS, Observatoire Astronomique de Strasbourg

Treasures Hidden in High Energy Catalogues IRAP, Toulouse, 23rd May, 2018





Cross-match tools

Cross-match tools and web-services (not exhaustive)

- Standalone tools
 - TOPCAT / STILTS: powerful general purpose tool, no probabilic cross-matches; Open Source (GPL), Java
 - NWAY: probabilistic cross-matches, able to account for photometry; Open Source, Python
 - C3, catsHTM: Python
- Web Services
 - SQL based: CasJobs (SDSS, Galex, ...), TAP (IVOA standard) services, SkyQuery, ...
 - Not SQL: CDS Cross-match service (asynchronous)
 - HTTP API: CDS Cross-match service (TOPCAT / STILTS, wget/curl, astroquery)
 - ARCHES tool: HTTP API + dedicated language, complexe cross-matches, probabilities

Main focus

- Roughly reproducing Salvato et al. (2018) results (J/MNRAS/473/4937/xmmslew2) and comparing them with the ARCHES tool + CDS classification (prototype) service
 - Goal: are two independent tools with similar methods provide coherent results?

NWAY / ARCHES: input data

Input data provide by Mara Salvato:

- XMM Slew survey Release 2: 17672 / 29393 sources
 - ▶ |b| > 15°, no SMC, noLMC
- 2' extraction in AllWISE: 1009830 sources
 - Made using the CDS Xmatch service through TOPCAT?
- Surface area of both datasets



NWAY / ARCHES: input data

- Remove large positional errors:
 - Less noise in the normalised distance histograms
 - Finer prior estimation in the ARCHES tool
 - XMM: 958 sources removed (5%)
 - AllWISE: 834 sources removed (< 0.1%)</p>



NWAY / ARCHES: input params

- Adjust common surface area to account for border effects in priors computation
 - Not negligible for numerous 2 arcmin cones
 - $n_{spur} \propto \rho_X \rho_{IR} \frac{\Omega_{common} \Omega_{common}}{\Omega_{common}} \chi_{ell}$
 - χ -ellipse must be in the common surface area
 - ▶ \Rightarrow for a cone search area, the center of the χ -ellipse must be in a smaller cone



- Legend of the figure:
 - Hatched area: Ω_{common}
 - Uniformly filled area:
 Ω_{common}_
 - ► Orange: *χ* association ellipse

NWAY / ARCHES: input script

Write and ARCHES cross-match script

```
# Load and set the XMM data to be cross-matched
get FileLoader file=XMMSL2_exgal_fewcol_2017APR12.fits
where RADEC ERR < 10.0
set pos ra=RA dec=DEC
set poserr type=CIRCLE param1=RADEC_ERR/sgrt(2)
set cols *
prefix x
# Load and set the AllWISE data to be cross-match
get FileLoader file=candidate_ALLWISE_counterparts_unique_2017APR12.fits.gz
where eeMaj < 0.75
set pos ra=RA dec=DEC
set poserr type=ELLIPSE param1=eeMai param2=eeMin param3=eePA
set cols *
prefix w
# Perform the cross-match, add the angular distance and save the result
xmatch probaN_v1 joins=I completeness=0.9973 area_w=0.01851769294883401575
               area_x=0.01851769294883401575 area_xw=0.01388
merge dist mec
save xmmslew2 vs allwise fits fits
```

NWAY / ARCHES: result

- Cross-match result: 23813 associations
- Number of spurious matches (*n*.*p*(*spur*)) overestimated (?)



NWAY / ARCHES: position only

NWAY vs ARCHES purely positional probabilities

► scatter ($\sigma = 0.1$): priors, bi-normal (dxdy) vs Rayleigh ($2\pi r dr$) (Eq. 150 vs Eq. 149 in Pineau et al. 2017).



NWAY / ARCHES: photometry

- Use photometric information to help separating good/spurious matches
- Purely positional cross-match

$$p(real|x) = \frac{p(real)p(x|real)}{p(real)p(x|real) + p(spur)p(x|spur)}$$

▶ x: Mahalanobis distance; p(x|real): Rayleigh; p(x|spur): Poisson.

Adding photometric likelihoods

 $p(real|x, \vec{m}) = \frac{p(real)p(x|real)p(\vec{m}|real)}{p(real)p(x|real)p(\vec{m}|real) + p(spur)p(x|spur)p(\vec{m}|spur)}$

• \vec{m} : position of the match in a photometric parameter space

NWAY / ARCHES: photometry

• Purely photometric probabilities

 $p(real|\vec{m}) = rac{p(real)p(\vec{m}|real)}{p(real)p(\vec{m}|real) + p(spur)p(\vec{m}|spur)}$

- ullet ~ few supervised automated classification methods
 - Linear Discriminant Analysis (LDA)
 - Kernel Density Classification (see Richards et al. 2004)

Stars/QSO photometric separation

• Goal of the classification: separate good and spurious matches

Automated classification

- Supervised / unsupervised (or clustering)
- Full/Reduced set of parameters (curse of dimensionality in k-NN like approaches)
- Supervised methods:
 - decision trees: OC1, Random forest, ...;
 - neural networks: SOM, LVQ, MLP, ...;
 - SVM
 - Bayes based: k-NN, KDC, LDA, ...
- Tools: R, Python (scikit -learn), ...
- Recurrent problem: tune input parameters to avoid over-fitting/under-fitting the LS

Automated classification

- Most important than the algorithm
 - Separability of classes in the parameter space
 - Learning samples quality / representativity
- Choosing a classif algo:
 - Easy to understand and to interpret
 - Naturally provide probabilities
 - Fast, easily reproducible (no random aspects)
- Personal choice: Kernel Density Classification

NWAY / ARCHES: photometry

- From Salvato et al. (2018): W2 vs W1-W2
- Learning samples arbitrary defined:
 - Good: d<6" && RADEC_ERR<8 && proba_xw>0.75
 - Spurious: d>13" && proba_xw<0.05</p>



Classification service

- 3 CSV files: all matches, good matches, spurious matches
- Each file contains: *id*, *w*2, *w*1 *w*2
- Using the CDS prototype service:

```
# Put the data files into the distant server
./classif.bash put good slew_vs_allwise.good.csv # 4565 rows
./classif.bash put spur slew_vs_allwise.spur.csv # 3082 rows
./classif.bash put data slew_vs_allwise.all.csv # 23799 rows
# Performs the classification of the data and save the result
./classif.bash kdc samplepoint -k 75 -p good:0.425\;spur:0.575 -ho > result.csv
# Ask for the confusion matrix by self-classifying the LS
./classif.bash kdc samplepoint -k 75 -p good:0.425\;spur:0.575 -cr
```

Confusion matrix:

actual \predicted	good	spurious
good	85.96%	14.04%
spurious	9.73%	90.27%

NWAY / ARCHES: photometry

- Likelihoods (distributions) computed by kernel smoothing (sample point estimator, k=75)
 - left: $p(\vec{m}|good)$
 - right: $p(\vec{m}|spur)$



NWAY / ARCHES: photometry

- Left: classification result p(good)
- Right: binary classification Good/Spurious (p(good) > 0.5, p(good) < 0.5)



Merging with positional proba

 Accounting for photometric likelihoods (simplified Eq. 154 of Pineau et al. 2017)

$$p(real|x, \vec{m}) = rac{p(real|x)p(\vec{m}|real)}{p(real|x)p(\vec{m}|real) + (1 - p(real|x))p(\vec{m}|spur)}$$





- Left: positional probabilities
- Right: probabilities accounting for photometric likelihoods

NWAY / ARCHES: proba id



• Clearer separation of low and high probabilities

NWAY / ARCHES: proba id



NWAY / ARCHES

Comparing NWAY and ARCHES outputs





Testing the same method to cross-match XMM and SDSS



http://cdsxmatch.u-strasbg.fr

Quick-and-dirty test in 4 dimensions

- Simple 10 arcsec cross-match
- Keep only primary unresolved objects having a clean photometry
- Mahalanobis distance: $d_{\sigma} \approx \frac{d}{\sqrt{\left(\frac{sc_POSERR}{\sqrt{2}}\right)^2 + RA_ERR \times DE_ERR}}$
- Lazy learning samples definition:
 - ★ 19676 "real" associations: d < 1" && $d_{\sigma} < 1.5$
 - ★ 7784 "spurious" associations: d > 8" && $d_{\sigma} > 6$
- User defined prior p(cp) going to d_{σ,max} = 5
- From Eq. 149 of Pineau et al. (2017):

$$p(cp|d_{\sigma}) = rac{1}{1+rac{1-p(cp)}{p(cp)}}rac{2}{d_{\sigma,max}^2e^{-rac{d_{\sigma}^2}{2}}}$$

Using the CDS prototype service:

```
# Put the data files into the distant server
./classif.bash put good xmm_sdss8.unres.good.csv # 19676 rows
./classif.bash put spur xmm_sdss8.unres.spur.csv # 7784 rows
./classif.bash put data xmm_sdss8.unres.all.csv
# Performs the classification of the data and save the result
./classif.bash kdc samplepoint -k 25 -p good:0.55\;spur:0.45 -ho > result.csv
# Ask for the confusion matrix by self-classifying the LS
./classif.bash kdc samplepoint -k 25 -p good:0.55\;spur:0.45 -cr
```

Confusion matrix:

actual \predicted	good	spurious
good	86.91%	13.09%
spurious	12.28%	87.72%



Mean of the 4D KDC output probabilities in

● u - g vs g - r

•
$$r - i vs \propto F_X/F_r$$



XMM DR7 vs SDSS DR8

Using 4D photometric likelihoods to compute final proba $p(cp|d_{\sigma}, \vec{m})$, and considering:

- real matches as $p(cp|d_{\sigma},\vec{m}) > 0.5$
- spurious matches as $p(cp|d_\sigma, ec{m}) < 0.5$



XMM DR7 vs SDSS DR8

 u – g vs g – r diagrams of estimated as real and estimated as spurious associations.



Outliers

- Outliers automatic selection:
 - Select low likelihoods $p(\vec{m}|cp)$ and $p(\vec{m}|spur)$ and high p(cp|x);
 - Check sources having a high $p(\vec{m}|spur)$ and a high p(cp|x);
 - ► ...

Gaia DR2 vs PS1

- Checking PanSTARRS (STSCI / VizieR version) versus Gaia DR2 astrometric compatibility.
- ARCHES tool used to cross-match Gaia DR2 and PanSTARRS DR1 in 1400 XMM FOVs
- Simple 3 arcsec cross-match
 - Without taking into accounts PMs
 - Gaia DR2 positions computed at PS1 epoch

Gaia DR2 vs PS1



Results are better **NOT** taking into account Gaia DR2 PMs!!

Gaia DR2 vs PS1

Attempt to re-calibrate PS1 from Gaia DR2 positions (at PS1 epochs)



Improve results, but still not enough!!

• Rayleigh distribution assumption not satisfied!

Gaia DR2 vs SDSS DR12

Gaia DR2 PMs do improve the cross-match with SDSS DR12



Complications with 3 cats

- 3 catalogues (X, S, W)
- 5 possibilities (5 priors, 5 likelihoods)
 - XSP: one actual source;
 - XS_P, XP_S, X_SP: 2 actual sources
 - X_S_P: 3 actual sources.
- Photometry: need to build 5 learning samples, perform a 5 classes classification
 - On-going tests with XMM-SDSS-AllWISE

Complication with outer joins

- I want X (XMM) sources χ -compatible with S (SDSS) **AND** P (PanSTARRS)
 - ► Can be done iteratively: X → XS → XSP
- I want X (XMM) sources χ-compatible with S (SDSS) OR P (PanSTARRS)
 - Can't be done iteratively!!
 - ***** X χ -compatible with S
 - ***** X χ -compatible with P
 - ***** S (and XS) not χ -compatible with P
 - $\star \Rightarrow$ first step, XS, then nothing (XP missed!).
 - The ARCHES tool selects XS and XP, and remove them if XSP is also found.

Conclusion

- NWAY and ARCHES provides coherents results ($\sigma \approx$ 0.1)...
 - ... but probabilities have to be used with care
- One can use Bayes based supervised classification techniques to compute photometric likelihoods, idependently from the positional part
 - dimensionality reduction
 - confusion matrix minimisation to compute the "best" KS bandwidth
- Complexity increase dramatically with the number of catalogues
- Do not forget the positional cross-match assumptions: Rayleigh, Poisson.
 - they are not so often satisfied!

The Kernel Density Classif

- Original paper: Richards et al (2004)
 - ▶ star/quasar (c_1/c_2) classification from $\vec{x} =$ (u-g, g-r, r-i, i-z)
- Supervised method: requires a learning sample for each class c_i
- Direct application of the Bayes' formula

$$p(c_i|\vec{x}) = \frac{p(c_i)p(\vec{x}|c_i)}{\sum\limits_{j=1}^{n} p(c_j)p(\vec{x}|c_j)}$$
(1)

- c_i: object class
- \vec{x} : vector in the parameter space
- *p*(*c_i*): user defined priors
 - ★ iterate while priors ≠ posteriors means
- ▶ $p(\vec{x}|c_i)$: likelihoods (p.d.f) computed by kernel smoothings (KS)
 - ★ one KS by learning sample class

Histogramming vs KS in 1D

- KS: density = sum of kernels centered around each data point
- Normalised density = probability density function (p.d.f)



Credits: https://en.wikipedia.org/wiki/File:Comparison_of_1D_histogram_and_KDE.png

Kernel smoothing in 2D

- KS: density = sum of 2D kernels (e.g. 2D Gaussians) centered around each data point
- Normalised density = probability density function (p.d.f)



Credits: Comaniciu, D. and Meer, P. (1997)

Kernels



Credits: https://en.wikipedia.org/wiki/File:Kernels.svg

• We use only the multivariate Epanechnikov kernel

- finite support (unlike Gaussian kernels)
- theoretically the best (even if it is not that important)

Various Kernel Smoothing

- Fixed bandwidth: all kernels have the same bandwidth
- Variable/Adaptative bandwidth
 - balloon estimator:
 - ★ 1 fixed bandwidth per density estimation
 - bandwidth = distance to the measurement point's kth-NN
 - knn averaging: balloon estimator with a uniform kernel
 - sample-point estimator:
 - ★ 1 bandwidth per data point in the LS
 - \star data point bandwidth = distance to the data point's kth-NN